

modelMagnetic fields in matter $\vec{M}(\vec{r})$

$$\vec{B} \equiv c \vec{\nabla} \times \vec{M} + c \vec{M} \times \hat{n}$$

$\uparrow$ volume current $\uparrow$ surface.

$$\vec{B} \rightarrow \vec{B} - 4\pi \vec{M} \equiv \vec{H}$$

permanent magnets
 paramagnetism
 diamagnetism

Today Electromotive Force

Electromotive Force

magnetic flux $\Phi = \int_S \vec{B} \cdot d\vec{s}$

Flux is independent of the surface

prove

$$\int_V \text{div } \vec{B} d^3r = 0 \Rightarrow \int_{\partial V} \vec{B} \cdot d\vec{s} = 0$$

$$\Rightarrow \int_{S_1} \vec{B} \cdot d\vec{s} + \int_{S_2} \vec{B} \cdot d\vec{s} = 0$$

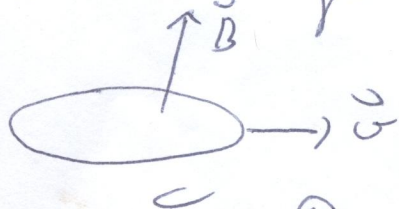
if we choose S_1 the normal in the same direction this gives

$$\int_{S_1} \vec{B} \cdot d\vec{s} - \int_{S_2} \vec{B} \cdot d\vec{s} = 0 \quad \text{qed}$$

An electromotive force occurs if a conductor moves through a magnetic field. The reason is that the electrons feel the Lorentz force

$$\vec{F}_L = e \frac{\vec{v}}{c} \times \vec{B}$$

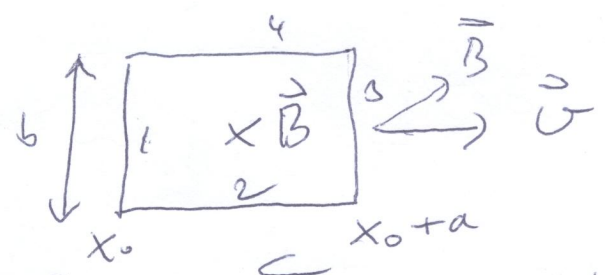
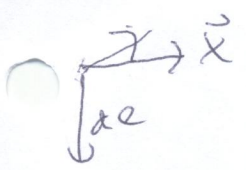
we can also interpret this as an effective electric field $\vec{E}_{\text{eff}} = \frac{\vec{v}}{c} \times \vec{B}$



Electromotive force

$$\mathcal{E}_{\text{eff}} = \oint_C \vec{E} \cdot d\vec{l} = \int_C \frac{\vec{v}}{c} \times \vec{B} \cdot d\vec{l}$$

Example



$\vec{B} = \text{constant}$

$$\frac{1}{c} \oint_C \vec{v} \times \vec{B} \cdot d\vec{r} = \frac{1}{c} \frac{d}{dt} \int_C \vec{X} \times \vec{B} \cdot d\vec{r}$$

$$= \frac{1}{c} \frac{d}{dt} \int_C \vec{B} \cdot d\vec{r} \times \vec{X}$$

integral only nonzero on vertical sides

$$= \frac{1}{c} \frac{d}{dt} \left(\int_1 \vec{B} \cdot d\vec{r} \times \vec{X} + \int_2 \vec{B} \cdot d\vec{r} \times \vec{X} \right)$$

$$B b x_0 - B b (x_0 + a)$$

$$= -\frac{1}{c} \frac{d}{dt} B A = -\frac{1}{c} \frac{d}{dt} \Phi$$

flux.

Next we will prove this in general

$$\mathcal{E}_{\text{ef}} = -\frac{1}{c} \frac{d\Phi}{dt}$$

the Flux changes due to a moving circuit.

Faraday Law same formula but then the

changes due to the time dependence of the magnetic field.

Lecture # 17

(53a)

electromotive force

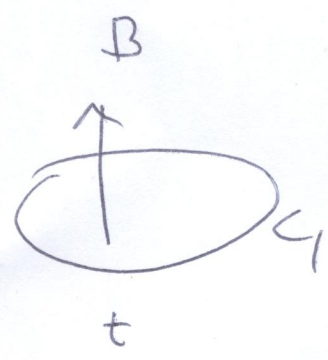
$$\mathcal{E} = - \frac{1}{c} \frac{d\Phi}{dt}$$

$$\Phi = \int \vec{B} \cdot d\vec{A}$$

$$= \oint_C \vec{E} \cdot d\vec{\ell} = \int \frac{\vec{\sigma}}{c} \times \vec{B} \cdot d\vec{\ell}$$

Today: Faraday for arbitrary circuit

flux $\phi = \int \vec{B} \cdot \vec{ds} = \int \vec{A} \cdot d\vec{\ell}$
" $\vec{\nabla} \times \vec{A}$



$C_2 = C_1 + \delta C_1$

$C_1: \vec{x}(\tau)$
 $C_2: \vec{x}(\tau) + \delta \vec{x}(\tau)$
 $x(0) = x(1)$
 $0 \leq \tau < 1$
 $d\vec{\ell} = \frac{d\vec{x}}{d\tau} d\tau$

$\delta\phi = \oint_{C_2} \vec{A} \cdot d\vec{\ell} - \oint_{C_1} \vec{A} \cdot d\vec{\ell}$

$= \int_0^1 d\tau A_i (x(\tau) + \delta x(\tau)) \frac{d(\vec{x} + \delta \vec{x})_i}{d\tau}$

$- \int_0^1 d\tau A_i (x(\tau)) \cdot \frac{d x(\tau)_i}{d\tau}$

$= \int_0^1 d\tau \left(\partial_k A_i(\vec{x}) \delta x_k \frac{dx_i}{d\tau} + A_i \frac{d(\delta x)_i}{d\tau} \right)$

// partial integration

$\left(-\frac{d}{d\tau} A_i \right) (\delta x_i)$

$\Rightarrow \delta\phi = \int_0^1 d\tau \left(\partial_k A_i - \partial_i A_k \right) \times \delta x_k \frac{dx_i}{d\tau}$

$= - \frac{d A_i}{d x_p} \frac{d x_p}{d\tau} \delta x_i$

$$d\vec{r} \frac{d\vec{x}}{d\tau} = d\vec{\ell}$$

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$$\Rightarrow \delta\phi = \int_0^1 d\tau \left(\partial_\mu A_i - \partial_i A_\mu \right) \cdot \delta x_\mu$$

$$\text{Let us look at } (\delta \mathbf{x} \times \vec{B})_i = (\delta \mathbf{x} \times (\vec{\nabla} \times \vec{A}))_i$$

$$= \epsilon_{ijk} \delta x_j \epsilon_{kpr} \partial_{x_p} A_r$$

$$= (\delta_{ip} \delta_{jq} - \delta_{iq} \delta_{jp}) \delta x_j \partial_{x_p} A_q$$

$$= \delta x_q \partial_{x_i} A_q - \delta x_j \partial_{x_j} A_i$$

$$\text{So } \delta\phi = - \int_0^1 d\tau (\delta \mathbf{x} \times \vec{B}) \cdot d\vec{\ell}$$

$$\Rightarrow -\frac{1}{c} \frac{\delta\phi}{\delta\tau} = + \frac{1}{c} \int_0^1 d\tau (\frac{d\vec{x}}{d\tau} \times \vec{B}) \cdot d\vec{\ell}$$

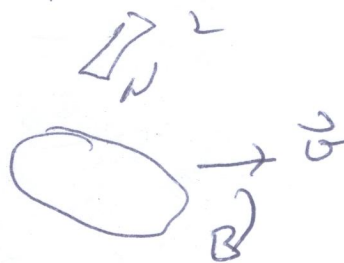
$$= \frac{1}{c} \int \frac{d\vec{x}}{d\tau} \times \vec{B} \cdot d\vec{\ell}$$

$$= \mathcal{E} dt$$

Faraday's Law

move the magnet and keep the circuit

Fixed



Galilean invariance Physics in (55)
frame A) and in frame B) is the same

$$Q = \int I dt = \int \frac{\mathcal{E}}{R} dt$$

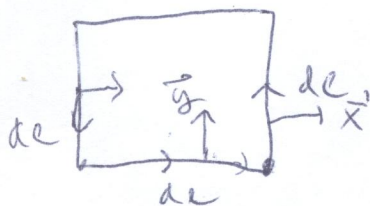
Same amount of charge is transferred.

$$\Rightarrow \mathcal{E}_A = \mathcal{E}_B$$

Faraday's law $\mathcal{E} = - \frac{d\phi}{dt}$

Paradox

$\vec{B} = \text{constant}$



$$\begin{aligned} \mathcal{E} &= \frac{1}{c} \oint \vec{v} \times \vec{B} \cdot d\vec{l} \\ &= \frac{1}{c} \oint \frac{d\vec{x}}{dt} \times \vec{B} \cdot d\vec{l} \\ &= \frac{1}{c} \oint d\vec{l} \times \frac{d\vec{x}}{dt} \cdot \vec{B} \\ &= \frac{d}{dt} \underbrace{\frac{1}{c} \oint d\vec{l} \times \vec{x} \cdot \vec{B}}_{2A} \end{aligned}$$

↑ wrong

solution
on t.

the contour also depends

parameterization of C

$$x(\tau), 0 \leq \tau < 1$$

$$x(0) = x(1)$$

$$\mathcal{E} = \frac{1}{c} \int_0^1 d\tau \underbrace{\frac{d\vec{x}}{d\tau}}_{d\vec{\ell}} \times \frac{d\vec{x}}{d\tau} \cdot \vec{B}$$

$$= \frac{1}{c} \frac{d}{dt} \int_0^1 d\tau \frac{d\vec{x}}{d\tau} \times \vec{x} \cdot \vec{B} - \frac{1}{c} \int_0^1 d\tau \frac{d\dot{\vec{x}}}{d\tau} \times \vec{x} \cdot \vec{B}$$

$$- \frac{1}{c} \frac{d}{dt} \vec{A} \cdot \vec{B}$$

(see previous page)

$$\begin{aligned} &+ \frac{1}{c} \int_0^1 d\tau \vec{x} \times \frac{d\dot{\vec{x}}}{d\tau} \cdot \vec{B} \\ &\stackrel{\text{Part Int}}{=} + \frac{1}{c} \int_C \vec{v} \times d\vec{\ell} \cdot \vec{B} \\ &= -\frac{1}{c} \int_C \vec{v} \times \vec{B} \cdot d\vec{\ell} \end{aligned}$$

$$\mathcal{E} = \frac{1}{c} \oint \vec{v} \times \vec{B} \cdot d\vec{\ell}$$

$$\Rightarrow -\frac{1}{c} \frac{d\Phi}{dt} = \mathcal{E}$$

$$\Rightarrow \mathcal{E} = -\frac{1}{c} \frac{d\Phi}{dt}$$

Lecture #10

57d

$$\mathcal{E} = -\frac{1}{c} \frac{d\phi}{dt}$$

Paradox



B const!

$$\begin{aligned}\mathcal{E} &= \frac{1}{c} \int \vec{v} \times \vec{B} \cdot d\vec{\ell} \\ &= \frac{d}{dt} \frac{1}{c} \int \vec{x} \times \vec{B} \cdot d\vec{\ell} \\ &= \frac{1}{c} \frac{d}{dt} \underbrace{\int d\vec{\ell} \times \vec{x} \cdot \vec{B}}_{-2A}\end{aligned}$$

$$\begin{aligned}\text{missing term } & -\frac{1}{c} \int \frac{d\vec{\ell}}{dt} \times \vec{x} \cdot \vec{B} \\ &= -\frac{1}{c} \int \frac{d}{dt} \frac{d\vec{x}}{dt} \times \vec{x} \cdot \vec{B} \\ \text{PT} &= +\frac{1}{c} \int \frac{d\tau}{dt} \vec{x} \times \frac{d\vec{x}}{dt} \cdot \vec{B} \\ &= \frac{1}{c} \int \frac{d\tau}{dt} \vec{B} \times \vec{x} \cdot \frac{d\vec{x}}{dt} \frac{dt}{d\tau} \\ &= -\frac{1}{c} \int \frac{d\tau}{dt} \vec{v} \times \vec{B} \cdot d\vec{\ell} \\ &= -\mathcal{E}\end{aligned}$$

$$\Rightarrow \mathcal{E} = -2A \cdot B - \mathcal{E}$$

$$\Rightarrow 2\mathcal{E} = 2AB$$

(oh)

Maxwell equation

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$$1) \vec{\nabla} \times \vec{E} = -\frac{1}{c} \partial_t B$$

$$2) \vec{\nabla} \cdot \vec{E} = 4\pi \rho$$

$$3) \vec{\nabla} \cdot \vec{B} = 0$$

$$4) \vec{\nabla} \times \vec{B} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$$

We will now argue that this term should be there

1) and 3) are consistent

$$\underbrace{\vec{\nabla} \cdot \vec{\nabla} \times \vec{E}}_{=0} = -\frac{1}{c} \partial_t \vec{\nabla} \cdot \vec{B} = 0$$

Continuity eq $\partial_t \rho + \vec{\nabla} \cdot \vec{j} = 0$

$$\partial_t \rho \neq 0 \Rightarrow \vec{\nabla} \cdot \vec{j} \neq 0$$

$$\text{and } \underbrace{\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B})}_{=0} = \frac{4\pi}{c} \vec{\nabla} \cdot \vec{j} \neq 0$$

Maxwell solved this by adding an extra term to 4

$$\vec{\nabla} \times \vec{B} = \frac{4\pi}{c} (\vec{j} + \vec{j}_0)$$

$\vec{j}_0$ displacement current

To be consistent, we need that

(5)

$$\vec{\nabla} \cdot (\vec{j} + \vec{j}_0) = 0$$

$$\Rightarrow \vec{\nabla} \cdot \vec{j}_0 = -\vec{\nabla} \cdot \vec{j} = +\frac{\partial \rho}{\partial t}$$

$$= \frac{1}{4\pi} \vec{\nabla} \cdot \frac{\partial \vec{E}}{\partial t}$$

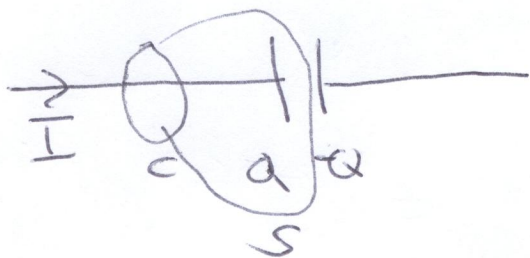
$$\Rightarrow \vec{j}_0 = \frac{1}{4\pi} \frac{\partial \vec{E}}{\partial t} + \vec{\nabla} \times \vec{Q}$$

The simplest choice $\vec{Q} = 0$
appeared to be the right choice.

$$\Rightarrow \text{ME 4): } \vec{\nabla} \times \vec{B} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$$

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Example of displacement current



$$\oint_C \vec{B} \cdot d\vec{l} = \frac{4\pi}{c} I$$

$$\equiv \int_S \vec{\nabla} \times \vec{B} \cdot d\vec{S}$$

choose S through capacitor.

~~which~~ without displacement current
we have that $\vec{\nabla} \times \vec{B} = \frac{4\pi}{c} \vec{j} = 0$

with displacement current

$$\vec{\nabla} \times \vec{B} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \partial_t \vec{E}$$

$$\Rightarrow \int_S \vec{\nabla} \times \vec{B} \cdot d\vec{S} = \int_S \frac{1}{c} \partial_t \vec{E} \cdot d\vec{S}$$

$$= \frac{1}{c} \partial_t \int_S \vec{E} \cdot d\vec{S}$$

we can close
 S because
 $\vec{E} = 0$ inside C

$$= \frac{1}{c} \partial_t \int_V \underbrace{\text{div } \vec{E}}_{4\pi \rho} \cdot dV$$

$$= \frac{1}{c} 4\pi \partial_t Q = \frac{4\pi}{c} I \quad \underline{\text{okay}}$$

Lecture # 19

60th

$\nabla \cdot \vec{E}$

$$\nabla \times \vec{E} = -\frac{1}{c} \frac{\partial \vec{B}}{\partial t}$$

Faraday

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \cdot \vec{E} = 4\pi \rho$$

$$\nabla \times \vec{B} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$$

displacement
current

necessary for consistency

Today : - Magnetic energy
- momentum tensor

Faraday's law

$$\mathcal{E} = - \frac{d\phi}{dt}$$



$$\oint_C \vec{E}_{\text{eff}} \cdot d\vec{e} = - \frac{d}{dt} \int \vec{B} \cdot d\vec{A}$$

|| stoke ||

$$\int \vec{\nabla} \times \vec{E} \cdot d\vec{A}$$

True for arbitrary loops

$$\Rightarrow \vec{\nabla} \times \vec{E} = - \frac{d}{dt} \vec{B}$$

differential form of Faraday's law.

Magnetic energy

a magnetic field acting on a current transfers energy to the current.

The loss of energy ^{of the field} per second is given by

$$- \frac{dW}{dt} = \int d^3r \vec{E} \cdot \vec{j} = \int d^3r \vec{E} \cdot \frac{c}{4\pi} \vec{\nabla} \times \vec{H}$$

$$= \int d^3r \frac{c}{4\pi} \vec{H} \cdot \vec{\nabla} \times \vec{E}$$

$$= - \frac{c}{4\pi} \int d^3r \partial_t \vec{B} \cdot \vec{H}$$

$$B = \mu H$$

$$= - \frac{c}{8\pi} \partial_t \int d^3r (\vec{B} \cdot \vec{H})$$

$$\Rightarrow W = \frac{1}{8\pi} \int d^3r \vec{B} \cdot \vec{H}$$

$$dW = \sum_i q_i \vec{E}_i \cdot d\vec{s}$$

$$\frac{dW}{dt} = - \sum_i q_i \vec{E}_i \cdot \frac{d\vec{s}}{dt}$$

$$= - \int d^3r \vec{E}(r) \underbrace{\rho(r)}_{\vec{j}}$$

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We can rewrite this in terms of the vector potential.

$$W = \frac{1}{\mu_0} \int d^3r \vec{B} \cdot \vec{H} = \frac{1}{\mu_0} \int d^3r \vec{\nabla} \times \vec{A} \cdot \vec{H}$$

$$= \frac{1}{\mu_0} \int d^3r \epsilon_{ijk} \partial_j A_k \cdot H_i$$

$$= -\frac{1}{\mu_0} \int d^3r \epsilon_{ijk} A_k \partial_j H_i$$

$$= \frac{1}{\mu_0} \int d^3r \epsilon_{kji} A_k \partial_j H_i$$

$$= \frac{1}{\mu_0} \int d^3r \vec{A} \cdot \underbrace{\vec{\nabla} \times \vec{H}}_{\frac{1}{\epsilon} \vec{j}}$$

$$W = \frac{1}{2\epsilon} \int d^3r \vec{A} \cdot \vec{j}$$

For a circuit this becomes $d^3r \vec{j} = I d\vec{\ell}$

$$W = \frac{1}{2\epsilon} \oint \vec{A} \cdot I d\vec{\ell}$$

$$= \frac{1}{2\epsilon} \int_S I \underbrace{\vec{\nabla} \times \vec{A}}_{\vec{B}} \cdot d\vec{A} = \frac{1}{2\epsilon} I \Phi_{\text{flux}}$$

magnetic field depend linearly on the currents $\Rightarrow \Phi_i = \epsilon \sum_j \underset{\substack{\uparrow \\ \text{coefficients of induction}}}{L_{ij}} I_j$

$$\Rightarrow W = \frac{1}{2} \sum I_i L_{ij} I_j$$

Momentum tensor

$$\vec{F} = \frac{1}{c} \int_V d^3r \vec{j} \times \vec{B}$$

$$\vec{j} = \sum_i q_i \vec{v}_i \delta(\vec{r} - \vec{r}_i)$$

↑

force
of field on current

$$\vec{\nabla} \times \vec{B} = \frac{4\pi}{c} \vec{j}$$

$$\Rightarrow F = \frac{1}{4\pi} \int_V d^3r \frac{(\vec{\nabla} \times \vec{B}) \times \vec{B}}{-\vec{B} \times (\vec{\nabla} \times \vec{B})}$$

$$F_k = \frac{1}{4\pi} \int_V d^3r B_i \partial_k B_i - B_i \partial_i B_k$$

$$= -\frac{1}{4\pi} \int_V d^3r \frac{1}{2} \partial_k \vec{B}^2 - \partial_i (B_i B_k)$$

note that $\partial_i B_i = 0$

$$= \frac{1}{4\pi} \int_V d^3r \partial_i (B_i B_k - \frac{1}{2} \delta_{ik} \vec{B}^2)$$

$$= \int_{\partial V} da n_i T_{ik}$$

momentum tensor

$$T_{ik} = \frac{1}{4\pi} (B_i B_k - \frac{1}{2} \delta_{ik} \vec{B}^2)$$

Force on charges and current

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✓

$$\vec{F} = \int d^3r \left(\rho \vec{E} + \frac{1}{c} \vec{j} \times \vec{B} \right)$$

$$\frac{1}{4\pi} \vec{\nabla} \cdot \vec{E} \quad \frac{1}{4\pi} (\vec{\nabla} \times \vec{B}) - \frac{1}{4\pi} \partial_t \vec{E}$$

$$\Rightarrow F_i = \frac{1}{4\pi} \int d^3r \left(E_i \partial_k E_k - \frac{1}{c} (\vec{E} \times \vec{B})_i + ((\vec{\nabla} \times \vec{B}) \times \vec{B})_i \right)$$

$$E_i \partial_k E_k = \partial_k (E_i E_k) + E_k \partial_i E_k - E_k \partial_k E_i$$

$$= \partial_k (E_i E_k - \frac{1}{2} \delta_{ik} \vec{E}^2) + E_k (\partial_i E_k - \partial_k E_i)$$

$$(\vec{E} \times (\vec{\nabla} \times \vec{E}))_i = E_k \epsilon_{ikp} \epsilon_{prs} \partial_r E_s$$

$$\stackrel{H}{=} -\frac{1}{c} \partial_t B = E_k \partial_i E_k - E_k \partial_k E_i$$

$$((\vec{\nabla} \times \vec{B}) \times \vec{B})_i = -\vec{B} \times (\vec{\nabla} \times \vec{B}) = -B_k \partial_i B_k + B_k \partial_k B_i$$

$$= \partial_k (B_k B_i - \frac{1}{2} \delta_{ik} \vec{B}^2)$$

$$\Rightarrow F_i = - \int \frac{d^3r}{4\pi c} \partial_t (\vec{E} \times \vec{B}) + \int d^3r \partial_k T_{ik}$$

$$T_{ik} = E_i E_k - \frac{1}{2} \delta_{ik} \vec{E}^2 - \frac{1}{2} \delta_{ik} \vec{B}^2$$

$$F_i = - \int \frac{d^3r}{4\pi c} \partial_t (\vec{E} \times \vec{B})_i + \int_{\partial V} ds n_i T_{ki}$$

$\parallel$
 $\frac{d \vec{P}_{\text{mech}}}{dt}$

$\uparrow$
 $-\frac{d}{dt} \vec{P}_{\text{field}}$

$\uparrow$
 momentum flow through surface

$$\Rightarrow \frac{d}{dt} (\vec{P}_{\text{mechanical}} + \vec{P}_{\text{field}}) = \int_{\partial V} ds n_i T_{ki}$$

$\Rightarrow$ momentum of the em field is

$$\vec{P} = \frac{1}{4\pi c} \int d^3r (\vec{E} \times \vec{B})$$

The angular momentum of the

field is $\vec{L} = \frac{1}{4\pi c} \int d^3r \vec{r} \times (\vec{E} \times \vec{B})$

Lecture #20

(5) a

$$-\frac{dw}{dr} = \int d^3r \vec{E} \cdot \vec{j}$$

$$\Rightarrow W = \frac{1}{4\pi} \int d^3r \vec{B} \cdot \vec{H}$$
$$= \frac{1}{2c} \int d^3r \vec{A} \cdot \vec{j}$$

$$\phi_i = c \sum_j L_{ij} I_j$$

$$W = \frac{1}{2} \sum_{ij} I_i L_{ij} I_j$$

$$F_k = \int_{\partial V} da n_i T_{ik}$$

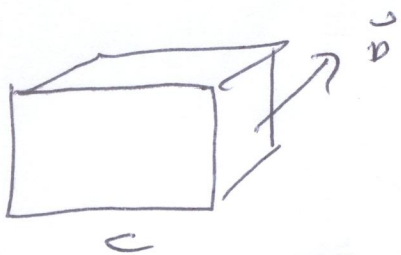
$$T_{ik} = \frac{1}{4\pi} (B_i B_k - \frac{1}{2} \delta_{ik} B^2)$$

Today Force on charges or currents

693
✓

Momentum density

$$\vec{p} = \frac{\vec{E} \times \vec{B}}{4\pi c}$$



momentum flow per unit area per second is $c \cdot \vec{p} \cdot \vec{n} = \frac{\vec{E} \times \vec{B}}{4\pi} \cdot \vec{n}$

energy $\vec{E} = pc$

$\Rightarrow$ energy flow per second per unit area

$$is \quad c \frac{\vec{E} \times \vec{B}}{4\pi} \cdot \vec{n}$$

$\vec{p} = c \frac{\vec{E} \times \vec{B}}{4\pi}$ is known as the

Poynting vector.

Energy conservation

64c)

$$E \cdot \frac{\partial D}{\partial t} + H \cdot \frac{\partial B}{\partial t} = E \cdot (c \nabla \times \vec{H} - 4\pi \vec{j}) - H c \cdot \vec{\nabla} \times \vec{E}$$

$$\Rightarrow -\frac{1}{4\pi} \int d^3r \vec{E} \cdot \frac{\partial \vec{B}}{\partial t} + H \cdot \frac{\partial \vec{B}}{\partial t} = \int d^3r \vec{j} \cdot \vec{E}$$

decrease of field energy

work done

$$+ \frac{c}{4\pi} \int d^3r \vec{E} \cdot \vec{\nabla} \times \vec{H} - \vec{H} \cdot \vec{\nabla} \times \vec{E}$$

energy flowing out

$$= \frac{c}{4\pi} \int d^3r \vec{\nabla} \cdot (\vec{E} \times \vec{H})$$

$$\vec{j} = \frac{c}{4\pi} \vec{E} \times \vec{H}$$

$$\vec{E} \cdot \vec{\nabla} \times \vec{H} - \vec{H} \cdot \vec{\nabla} \times \vec{E}$$

$$E_i \epsilon_{ijk} \partial_j H_k - H_i \epsilon_{ijk} \partial_j E_k$$

$$\epsilon_{jik} (-\partial_i H_k E_j + H_i \partial_j E_k) = \epsilon_{jik} (\partial_j H_k E_i - H_k \partial_j E_i)$$