

(7)

Integral form of Gauss law

$$\int_V dV \vec{\nabla} \cdot \vec{E} = \int_V dV 4\pi\rho$$

$$\int_{\partial V} da \vec{n} \cdot \vec{E}$$

e) Poisson Law

$$\begin{cases} \vec{\nabla} \cdot \vec{E} = 4\pi\rho \\ \vec{E} = -\vec{\nabla} \phi \end{cases} \Rightarrow \vec{\nabla}^2 \phi = -4\pi\rho$$

Poisson equation

$\rho = 0 \quad \vec{\nabla}^2 \phi = 0$ Laplace eq
 solutions are called harmonic functions

f) Uniqueness

A vector field that satisfies

$$\vec{\nabla} \cdot \vec{E} = 0 \quad \vec{\nabla} \times \vec{E} = 0$$

and vanishes at least as $1/r^2$ for $r \rightarrow \infty$
 vanishes everywhere

This follows from Liouville's theorem;
 if F is a harmonic function on \mathbb{R}^n
 and F is bounded from above or below
 then F is constant

Reason $\vec{E} = -\vec{\nabla} \phi$
 $\vec{\nabla}^2 \phi = 0$

$\vec{E} \propto \frac{1}{r^2}$ for $r \rightarrow \infty \Rightarrow \phi \propto \frac{1}{r}$ for $r \rightarrow \infty$

$\vec{\nabla} \cdot \vec{E} = 0 \Rightarrow \exists$ no singularities

$\Rightarrow \phi$ is bounded $\Rightarrow \phi = \text{constant}$

$\Rightarrow \vec{E} = 0$

Consequence: uniqueness theorem

$\vec{\nabla} \cdot \vec{E}_1 = 4\pi \rho_1$ } $\vec{\nabla} \cdot (\vec{E}_1 - \vec{E}_2) = 0$
 $\vec{\nabla} \cdot \vec{E}_2 = 4\pi \rho_2$ }

status $\Rightarrow \vec{\nabla} \times (\vec{E}_1 - \vec{E}_2) = 0$

$\Rightarrow \vec{E}_1 - \vec{E}_2 = 0$

Solutions of the Laplace eq

$\vec{\nabla}^2 \phi = 0$

$z = r \cos \theta$
 $x = r \sin \theta \cos \phi$
 $y = r \sin \theta \sin \phi$

Spherical coordinates

$\vec{\nabla}^2 \phi = \frac{1}{r} \frac{\partial^2}{\partial r^2} (r \phi) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \phi}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 \phi}{\partial \phi^2}$

$\phi = \frac{u(r)}{r} P(\theta) Q(\phi)$
 separation of variables

$$\nabla^2 \phi = \frac{P Q}{r} \partial_r^2 u + \frac{u Q}{r r^2 \sin \theta} \partial_\theta (\sin \theta \partial_\theta P) = 0$$

$$+ \frac{u P}{r r^2 \sin^2 \theta} \frac{\partial^2 Q}{\partial \varphi^2} = 0$$

divide by $u P Q$

$$\frac{u^{-1}}{r} \partial_r^2 u + \frac{P^{-1}}{r r^2 \sin \theta} \partial_\theta (\sin \theta \partial_\theta P)$$

$$+ \frac{Q^{-1}}{r r^2 \sin^2 \theta} \frac{\partial^2 Q}{\partial \varphi^2} = 0$$

$\times r^3$

$$r^2 u^{-1} \partial_r^2 u + \frac{P^{-1}}{\sin^2 \theta} \partial_\theta (\sin \theta \partial_\theta P)$$

$$+ \frac{Q^{-1}}{\sin^2 \theta} \frac{\partial^2 Q}{\partial \varphi^2} = 0$$

↑
only
depends on r

↗ only depends on θ, φ

⇒ both should be constant
because the equation is valid for
all r, θ, φ

$$r^2 u^{-1} \partial_r^2 u = c \Rightarrow \partial_r^2 u = c \frac{u}{r^2}$$

$$u = a r^{l+1} \Rightarrow l(l+1) r^{l-2} = c r^{l-2}$$

$$\Rightarrow c = l(l+1)$$

then

$$l(l+1) \sin^2 \theta + P^{-1} \partial_\theta (\sin \theta \partial_\theta P) + Q^{-1} \frac{\partial^2 Q^2}{\partial \varphi^2} = 0$$

$$\Rightarrow l(l+1) \sin^2 \theta + P^{-1} \partial_\theta (\sin \theta \partial_\theta P) = \left(\frac{\partial^2 Q^2}{\partial \varphi^2} \right) Q^{-1}$$

↑
function of θ

↑
function of φ

equal $\forall \theta, \varphi \Rightarrow$ they have to be constant

$$\Rightarrow Q^{-1} \frac{\partial^2 Q^2}{\partial \varphi^2} = -m^2 \Rightarrow Q = e^{\pm im\varphi}$$

$$\Rightarrow -\partial_\theta (\sin \theta \partial_\theta P) = l(l+1) \sin^2 \theta P - m^2 P$$

This equation is known as the Legendre equation.

The solutions are given by the associated Legendre polynomials

The combination PQ is given 11
 by $PQ = c' P_{em}(\cos\theta) e^{im\varphi} \equiv c' Y_{em}(\theta, \varphi)$

The constant c' is fixed by the spherical harmonics normalization sum rule

$$\sum_{m=-l}^l Y_{em}(\theta, \varphi) Y_{em}^*(\theta, \varphi) = \frac{2l+1}{4\pi}$$

$$Y_{00} = \frac{1}{\sqrt{4\pi}}$$

$$Y_{11} = -\sqrt{\frac{3}{8\pi}} \sin\theta e^{i\varphi} = -\sqrt{\frac{3}{8\pi}} \frac{x+iy}{r}$$

$$Y_{10} = \sqrt{\frac{3}{4\pi}} \cos\theta = \sqrt{\frac{3}{4\pi}} \frac{z}{r}$$

$$Y_{1-1} = \sqrt{\frac{3}{8\pi}} \sin\theta e^{-i\varphi} = \sqrt{\frac{3}{8\pi}} \frac{x-iy}{r}$$

We have found an infinite set of harmonic functions

$$\nabla^2 r^e Y_{em}(\theta, \varphi) = 0$$

$$e(e+1) = (-e-1)(-e-1) + 1$$

$$\Rightarrow u(r) = \frac{1}{r^e} \text{ is also solution}$$

$$\Rightarrow \nabla^2 \frac{1}{r+1} Y_{em}(\theta, \varphi) = 0$$

Most general solution of the Laplace eq.

$$\phi(r, \theta, \varphi) = \sum_{l=0}^{\infty} \sum_{m=-l}^l (A_{lm} r^l + B_{lm} r^{-l-1}) Y_{lm}(\theta, \varphi)$$

This is a complete set of functions

Strategy for solution of Poisson eq

$$\nabla^2 \phi = -4\pi\rho$$

then $\nabla^2(\phi + \phi_h) = -4\pi\rho$

↑
special solution

$$\nabla^2 \phi_h = 0$$

Generally we have a charge distribution and boundary conditions. The ϕ_h are determined by the boundary conditions.

outside charge distribution: $\rho = 0$
 $\Rightarrow \nabla^2 \phi = 0$ $\phi \rightarrow 0$ for $r \rightarrow \infty \Rightarrow A_{lm} = 0$

inside charge distribution: solution should be regular $\Rightarrow B_{lm} = 0$

Example 1: single charge at 0 13

$$\rho(r) = q \delta^3(r)$$

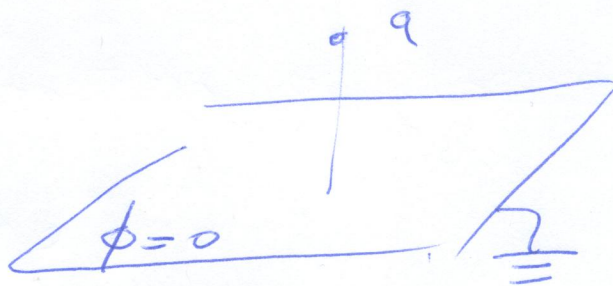
potential is spherically symmetric

\Rightarrow only $l=0, m=0$ is allowed

$$\Rightarrow \phi = A_{00} + B_{00} r^{-1}$$

$$\phi \rightarrow 0 \text{ for } r \rightarrow \infty = A_{00} = 0$$

Example 2



solution is axial symmetric

$\Rightarrow m=0$ $\phi \rightarrow 0$ for $r \rightarrow \infty$

$\Rightarrow A_{em} = 0$ for $r > 0$

$$\Rightarrow \phi = \sum B_{em} r^{-e-1} Y_{e0}(\theta, \varphi)$$

does not depend on φ .

$$\Sigma = 0 \quad \theta = \frac{\pi}{2}$$

$$\sum B_{em} r^{-e-1} Y_{e0}\left(\frac{\pi}{2}, \varphi\right) = 0$$

only odd l are possible

$$Y_{2k+1,0}\left(\frac{\pi}{2}, \varphi\right) = 0$$

$$\Rightarrow \phi = \sum_{l=0,2,4,\dots} a_l r^{-l-1} Y_{l,0}(\theta, \varphi) \quad (14)$$

look at the z -axis $\theta = 0 \Rightarrow$

$$\begin{aligned} \Rightarrow \phi &= \sum_{l=0} b_l r^{-l-1} \\ &= \sum_l \left(\frac{(-1)^l + 1}{2} \right) b_l r^{-l-1} \end{aligned}$$

for z should behaves as $\frac{q}{|z-a|}$ for $z \rightarrow a$

$\Rightarrow b_l = q a^l \cdot 2$ geometric series

on z axis $\phi = \frac{q}{r-a} - \frac{q}{r+a}$

$$\Rightarrow \phi = \sum_{l=0} (1 - (-1)^l) \frac{q a^l}{r^{l+1}} Y_{l,0}(\theta, \varphi) \quad r > a$$

for $r < a$ we use the solution with $r^l Y_{l,0}(\theta, \varphi)$

then on z axis

$$\phi = \sum_l b_l^< r^l \left(\frac{1 - (-1)^l}{2} \right)$$

$$\Rightarrow b_l^< = \frac{2 r^l q}{a^{l+1}} \left(\frac{1 - (-1)^l}{2} \right)$$

$$\begin{aligned} &= \frac{q}{a \left(1 - \frac{r}{a} \right)} - \frac{q}{a \left(1 + \frac{r}{a} \right)} \\ &= \frac{qr}{a-r} - \frac{q}{a+r} \end{aligned}$$