

# Unitary symplectic group

$$Sp(n) = Sp(2n, \mathbb{H}) \cap U(2n)$$

## Kramers degeneracy

$$\sigma_n \quad \sigma_n^* = -C^{-1} \sigma_n C$$

$$C = i\sigma_2$$

↑ charge conjugation matrix

spin orbit coupling  $H = \vec{L} \cdot \vec{S}$

$$\vec{S} = \frac{\hbar}{2} \sigma_n \quad \vec{L} = \vec{r} \times \vec{p}$$

$$\vec{L}^* = -\vec{L}$$

$$H^* = \vec{L}^* \cdot \vec{S}^* = + \vec{L} C^{-1} S C = C^{-1} H C$$

$$\Rightarrow [C K, H] = 0$$

↑ complex conjugation.

$$(CK)^2 = i\sigma_2 K i\sigma_2 K = i^2 \sigma_2^2 K^2 = -1$$

$$\Rightarrow \langle \psi, CK\psi \rangle = \langle CK\psi, (CK)^2 \psi \rangle^*$$

$$\Rightarrow \langle CK\psi, \psi \rangle^*$$

$$= -\langle \psi, CK\psi \rangle$$

CK is anti-unitary

$$\Rightarrow \langle \psi, CK\psi \rangle = 0$$

$$\text{if } H\psi = E\psi \text{ then } HCK\psi = CK H\psi = CK E\psi$$

$\Rightarrow CK\psi$  is eigenstate

it is independent of  $\psi \Rightarrow$

states are doubly degenerate.

This is Kramers degeneracy



SU(2)

$$u = \begin{pmatrix} x_0 + ix_3 & ix_1 + x_2 \\ ix_1 - x_2 & x_0 - ix_3 \end{pmatrix}$$

$$|x_0 + ix_3|^2 + |ix_1 + x_2|^2 = 1$$

$$x_0^2 + x_1^2 + x_2^2 + x_3^2 = 1$$

⇒ SU(2) ≅ 3 sphere

SU(2) rows are perpendicular

$$\begin{aligned} & (x_0 + ix_3)(ix_1 - x_2)^* + (ix_1 + x_2)^*(x_0 - ix_3) \\ &= +ix_0x_1 - x_0x_2 + x_3x_1 + ix_2x_3 \\ & \quad -ix_1x_0 + x_2x_0 - x_1x_3 - ix_2x_3 = 0 \end{aligned}$$

in terms of Pauli σ-matrices

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$u = x_0 \mathbb{1} + ix_k \sigma_k$$

$$[\sigma_i, \sigma_j] = 2i \epsilon_{ijk} \sigma_k \quad \sigma_i \sigma_j + \sigma_j \sigma_i = 2\delta_{ij}$$

the  $i\sigma_k$  are the generators of SU(2)

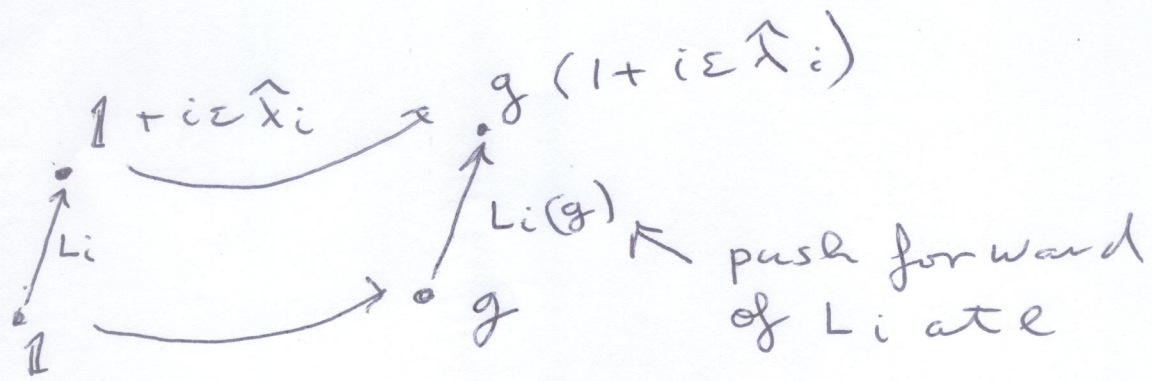
$$[i\sigma_k, i\sigma_l] = -f_{klm} i\sigma_m$$

$$f_{klm} = \epsilon_{klm}$$

↳ structure constants of the group



Invariant vector fields



$L_i(g)$  is in the tangent space of  $TG_g$

$L_i \in T\mathbb{R}^2$

Example  $SU(2)$

$$\begin{aligned}
 g(1 + i\varepsilon \sigma_3) &= x_0 + i\sigma_1 x_1 + i\sigma_2 x_2 + i\sigma_3 x_3 \\
 &\quad + x_0 i\varepsilon \sigma_3 + -x_1 \varepsilon \sigma_3 \sigma_1 \\
 &\quad \quad \quad - x_2 \varepsilon \sigma_2 \sigma_3 - x_3 \varepsilon \sigma_3 \sigma_3 \\
 &= (x_0 - \varepsilon x_3) + i\sigma_1 (x_1 - \varepsilon x_2) + i\sigma_2 (x_2 + \varepsilon x_1) \\
 &\quad \quad \quad + i\sigma_3 (x_3 + \varepsilon x_0)
 \end{aligned}$$

$$\begin{aligned}
 L_3 F(g) &= \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} (F(g(1 + i\varepsilon \sigma_3)) - F(g)) \\
 &= -x_2 \frac{\partial}{\partial x_1} + x_1 \frac{\partial}{\partial x_2} + x_0 \frac{\partial}{\partial x_3}
 \end{aligned}$$

$L_3 = \varepsilon_3 \kappa_l x_l \frac{\partial}{\partial x_l} + x_0 \frac{\partial}{\partial x_3}$

in general

$$L_p = \underbrace{\varepsilon_p \kappa_l x_l \frac{\partial}{\partial x_l}}_{\text{angular momentum operators}} + x_0 \frac{\partial}{\partial x_p}$$



$$x_1 \rightarrow x_1 - \epsilon x_2$$

$$x_2 \rightarrow x_2 + \epsilon x_1$$

$$x_3 \rightarrow x_3 + \epsilon x_0$$

$$\text{Then } x_0 = \sqrt{1 - x_1^2 - x_2^2 - x_3^2}$$

$$\rightarrow \sqrt{\underbrace{1 - x_1^2 - x_2^2 - x_3^2}_{x_0^2} + 2\epsilon x_1 x_2 - 2\epsilon x_1 x_2 - 2\epsilon x_0 x_3}$$

$$= x_0 \left( 1 - \frac{2\epsilon x_0 x_3}{x_0^2} \right)^{\frac{1}{2}} = x_0 - \epsilon x_3$$

which is exactly what it should be

$$[L_p, L_q]$$

$$\begin{aligned}
 [L_p, x_0 \frac{\partial}{\partial x_q}] &= \epsilon_{pke} x_k \frac{\partial}{\partial x_e} x_0 \frac{\partial}{\partial x_q} \\
 &\quad - x_0 \frac{\partial}{\partial x_q} \epsilon_{pke} x_k \frac{\partial}{\partial x_e} \\
 \frac{\partial}{\partial x_e} x_0 &= -\frac{x_e}{x_0} \\
 &= -\underbrace{\epsilon_{pke} x_k x_e}_{=0} \frac{\partial}{\partial x_q} \\
 &\quad - x_0 \epsilon_{pqe} \frac{\partial}{\partial x_e}
 \end{aligned}$$

$$[x_0 \frac{\partial}{\partial x_0}, L_q] = -x_0 \epsilon_{pqe} \frac{\partial}{\partial x_e}$$

$$L_p = \epsilon_{pke} x_k \frac{\partial}{\partial x_e}$$

$$\{[L_p, L_q] = -2 \epsilon_{pqe} L_e$$

$$\Rightarrow [L_p, L_q] = -2 \epsilon_{pqe} L_e$$

This work for all Lie groups

in general  $[L_i, L_j] = -f_{ij}^k L_k$



# Time reversal invariance for spin $\frac{1}{2}$ (97)

time reversal  $\vec{S} \rightarrow -\vec{S}$

in quantum mechanics  $T S T^{-1} = -S$

$$\vec{S} = \frac{\hbar}{2} \vec{\sigma}$$

$$T \left| \frac{1}{2} \frac{1}{2} \right\rangle = e^{i\delta} \left| \frac{1}{2} -\frac{1}{2} \right\rangle$$

$$\sigma_+ = (\sigma_1 + i\sigma_2)/2$$

$$\sigma_+ \left| \frac{1}{2} -\frac{1}{2} \right\rangle = \left| \frac{1}{2} \frac{1}{2} \right\rangle$$

$$\sigma_- = (\sigma_1 - i\sigma_2)/2$$

$$\sigma_- \left| \frac{1}{2} \frac{1}{2} \right\rangle = \left| \frac{1}{2} -\frac{1}{2} \right\rangle$$

$$T \sigma_- T^{-1} = \sigma_+ \quad T \sigma_+ T^{-1} = -\sigma_-$$

$$T \sigma_- \left| \frac{1}{2} \frac{1}{2} \right\rangle = T \left| \frac{1}{2} -\frac{1}{2} \right\rangle$$

$$\begin{aligned} -\sigma_+ \left| \frac{1}{2} \frac{1}{2} \right\rangle &= -\sigma_+ e^{i\delta} \left| \frac{1}{2} -\frac{1}{2} \right\rangle \\ &= -e^{i\delta} \left| \frac{1}{2} \frac{1}{2} \right\rangle \end{aligned}$$

$$\Rightarrow T \left| \frac{1}{2} -\frac{1}{2} \right\rangle = -e^{i\delta} \left| \frac{1}{2} \frac{1}{2} \right\rangle$$

$$\Rightarrow T = e^{i\delta} i\sigma_2 K (-1)$$

$$\begin{aligned} T \sigma_+ T^{-1} &= T (\sigma_1 + i\sigma_2) T^{-1} = -\sigma_1 + i\sigma_2 \\ &= -\sigma_- \end{aligned}$$

$$\begin{aligned} T \sigma_- T^{-1} &= T (\sigma_1 - i\sigma_2) T^{-1} = -\sigma_1 - i\sigma_2 \\ &= -\sigma_+ \end{aligned}$$

Note that  $T i T^{-1} = -i$

# The exponential map

90

Vector field  $X^a \partial_a$

Corresponding flow

$$\frac{dx^a}{dt} = X^a(x(t))$$

Let  $L_i$  be the vector field corresponding to  $i\lambda_i$  and

$$g(t) = e^{it\lambda_i} = 1 + it\lambda_i - \frac{1}{2}t^2\lambda_i^2 + \dots$$

$$\begin{aligned} g(t+\varepsilon) &= e^{i(t+\varepsilon)\lambda_i} = e^{it\lambda_i} e^{i\varepsilon\lambda_i} \\ &= g(t) (1 + i\varepsilon\lambda_i) \end{aligned}$$

$$\begin{aligned} \Rightarrow \frac{dg}{dt} &= \frac{1}{\varepsilon} (g(t+\varepsilon) - g(t)) \\ &= \frac{1}{\varepsilon} (g(t) (1 + i\varepsilon\lambda_i) - g(t)) \\ &\equiv L_i g(t) \end{aligned}$$

$$\Rightarrow g(t) = e^{L_i t}$$

with initial condition  $g(0) = 1$



## Right invariant vector fields

(99)

multiplication on the right to push forward a group element

$$(1 + i\varepsilon\sigma_3)g = g + i\varepsilon R_3 g$$

$$[R_i, R_j] = 2\varepsilon_{ijk} R_k$$

in general  $[R_i, R_j] = f_{ij}^k R_k$

$$[L_i, L_j] = -f_{ij}^k R_k$$

$$[L_i, R_j] = 0$$



# Maurer Cartan form

$$g = x^0 + i x^k \sigma^k$$

$$g^{-1} = x^0 - i x^k \sigma^k$$

we calculate  $dg g^{-1}$

$$dg = dx^0 + i dx^k \sigma^k$$

$$\parallel$$
$$-\frac{x_1 dx_1}{x_0} - \frac{x_2 dx_2}{x_0} - \frac{x_3 dx_3}{x_0}$$

$$dg g^{-1} = i \sigma_1 \left( x_0 + \frac{x_1^2}{x_0} \right) dx_1 + \left( x_3 + \frac{x_1 x_2}{x_0} \right) dx_2$$
$$+ \left( x_2 + \frac{x_1 x_3}{x_0} \right) dx_3$$
$$+ i \sigma_2 (\dots) + i \sigma_3 (\dots)$$

$$R_1 = x^0 \partial_1 + x^3 \partial_2 - x^2 \partial_3$$

$$dg g^{-1} = \omega_R = i \sigma_i \omega_k^i$$

Maurer-Cartan forms

$$\omega_R^1 = \left( x_0 + \frac{x_1^2}{x_0} \right) dx_1 + \left( x_3 + \frac{x_1 x_2}{x_0} \right) dx_2$$
$$+ \left( x_2 + \frac{x_1 x_3}{x_0} \right) dx_3$$

evaluate  $\omega_R^1 (R_1)$

$$dx_1 (\partial_1) = 1$$

$$dx_1 (\partial_2) = 0$$

$$dx_1 (\partial_3) = 0$$

$$\Rightarrow \omega_R^1 (R_1) =$$

$$\left( x_0 + \frac{x_1^2}{x_0} \right) x_0 + \left( x_3 + \frac{x_1 x_2}{x_0} \right) x_3$$
$$+ \left( x_2 + \frac{x_1 x_3}{x_0} \right) (-x_2)$$
$$= x_0^2 + x_1^2 + x_2^2 + x_3^2 = 1$$

see beginning of chapter 11



$$\omega_R^i(R_L) = \left( \cancel{x_0} + \frac{x_1 x_2}{\cancel{x_0}} \right) (-x_3) + \left( \cancel{x_1} + \frac{x_1 x_2}{\cancel{x_0}} \right) x_0 + \left( -\cancel{x_2} + \frac{x_1 x_2}{\cancel{x_0}} \right) x_1 - x^3 \partial_1 + x^0 \partial_2 + x^1 \partial_3 = 0$$

(101)

$$\Rightarrow \omega_R^k(R_L) = \delta_{kl}$$

Left invariant Maurer-Cartan form

$$g^{-1} dg = \omega_L = i \sigma_k \omega_L^k$$

$$\omega_L^i(L_j) = \delta_{ij}$$

$$d\omega_R = d(dg g^{-1}) = d^2 g \wedge g^{-1} - dg \wedge dg^{-1}$$

$$g^{-1}g = 1 \Rightarrow dg^{-1}g + g^{-1}dg = 0$$

$$\Rightarrow dg^{-1} = -g^{-1}dg g^{-1}$$

$$d\omega_R = dg \wedge (g^{-1}dg g^{-1}) = dg g^{-1} \wedge dg g^{-1} = \omega_R \wedge \omega_R$$

$$d^2 = 0$$

$$\begin{aligned} \omega_R \wedge \omega_R &= \omega_R^i \wedge \omega_R^j i \sigma_i i \sigma_j \\ &= \frac{1}{2} \omega_R^i \wedge \omega_R^j [i \sigma_i, i \sigma_j] \\ &= -\frac{1}{2} \omega_R^i \wedge \omega_R^j f_{ij}^k i \sigma_k \end{aligned}$$

Maurer-Cartan relations

$$d\omega_R^k = -\frac{1}{2} f_{ij}^k \omega_R^i \wedge \omega_R^j$$

For the left invariant forms we obtain

$$d\omega_L^k = \frac{1}{2} f_{ij}^k \omega_L^i \wedge \omega_L^j$$